ON THE MINIMUM OF ASYMPTOTIC TRANSLATION LENGTHS OF POINT-PUSHING PSEUDO-ANOSOV MAPS ON ONE PUNCTURED RIEMANN SURFACES

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ABSTRACT. We show that the minimum of asymptotic translation lengths of all point-pushing pseudo-Anosov maps on any one punctured Riemann surface is one.

1. Introduction and main results

Let S be a closed Riemann surface of genus p with n points removed. Assume that 3p-4+n>0. One can associate to S a curve complex $\mathcal{C}(S)$ which is equipped with a path metric $d_{\mathcal{C}}$. Let $\mathcal{C}_0(S)$ denote the set of vertices of $\mathcal{C}(S)$ that can be identified with the set of simple closed geodesics on S. See Section 2 for the definitions and terminology.

Following Farb-Leininger-Margalit [4], for any $u \in C_0(S)$, and any pseudo-Anosov map f of S, we can define $\tau_{\mathcal{C}}(f)$ as

(1.1)
$$\tau_{\mathcal{C}}(f) = \liminf_{m \to \infty} \frac{d_{\mathcal{C}}(u, f^{m}(u))}{m}.$$

It is known that $\tau_{\mathcal{C}}(f)$ does not depend on choices of vertices u in $\mathcal{C}_0(S)$ and is called the asymptotic translation length for the action of f on $\mathcal{C}(S)$. Bowditch [3] proved that $\tau_{\mathcal{C}}(f)$ for all pseudo-Anosov maps are rational numbers.

Let $\operatorname{Mod}(S)$ denote the mapping class group of S, and let $H \subset \operatorname{Mod}(S)$ be a subgroup. Denote by

$$L_{\mathcal{C}}(H) = \inf \{ \tau_{\mathcal{C}}(f) : \text{ for all pseudo-Anosov elements in } H \}.$$

By Masur–Minsky [8], there is a positive lower bound for $L_{\mathcal{C}}(H)$ that depends only on (p, n). For a closed surface S of genus p > 1, Theorem 1.5 of [4] asserts that

$$L_{\mathcal{C}}(\operatorname{Mod}(S)) < \frac{4\log(2+\sqrt{3})}{p\log(p-\frac{1}{2})}.$$

This particularly implies that $L_{\mathcal{C}}(\operatorname{Mod}(S)) \to 0$ as $p \to +\infty$. The lower and upper bounds for $L_{\mathcal{C}}(\operatorname{Mod}(S))$ were improved as

$$\frac{1}{162(2p-2)^2 + 30(2p-2)} < L_{\mathcal{C}}(\text{Mod}(S)) \le \frac{4}{p^2 + p - 4}$$

by a result of Gadre–Tsai [5].

Date: January 20, 2013.

¹⁹⁹¹ Mathematics Subject Classification. Primary 32G15; Secondary 30C60, 30F60.

Key words and phrases. Riemann surfaces, Pseudo-Anosov, Dehn twists, Curve complex, Filling curves.

The estimations of $L_{\mathcal{C}}(H)$ for certain subgroups H of $\operatorname{Mod}(S)$ were also considered in [4]. Let Γ_0 be the fundamental group of S. For any $k \geq 1$, let Γ_k be the kth term of the lower central series for Γ_0 . This chain of subgroups forms a filtration. Denote by \mathscr{N}_k the kernel of the natural homomorphism of $\operatorname{Mod}(S)$ onto $\operatorname{Out}(\Gamma/\Gamma_k)$. Then for the sequence of the subgroups \mathscr{N}_k , Theorem 6.1 of [4] states that for any k, a similar phenomenon emerges. That is,

$$L_{\mathcal{C}}(\mathcal{N}_k(S)) \to 0 \text{ as } p \to +\infty.$$

In this paper, we are mainly concerned with the case in which S contains only one puncture x. Then the subgroup $\mathscr{F} \subset \operatorname{Mod}(S)$ that consists of mapping classes projecting to the trivial mapping class on $\tilde{S} := S \cup \{x\}$ is highly non trivial and is isomorphic to the fundamental group $\pi_1(\tilde{S},x)$. It is well-known (Kra [7]) that \mathscr{F} contains infinitely many pseudo-Anosov elements, and the conjugacy class of a primitive pseudo-Anosov element of \mathscr{F} can be determined by an oriented primitive filling closed geodesic \tilde{c} on \tilde{S} in the sense that \tilde{c} intersects every simple closed geodesic on \tilde{S} .

In contrast to the above estimations for $L_{\mathcal{C}}(H)$ for various subgroups H of $\operatorname{Mod}(S)$, in the case where $H = \mathscr{F}$, we can view $L_{\mathcal{C}}(\mathscr{F})$ as a function of (p, n), and see that $L_{\mathcal{C}}(\mathscr{F})$ performs quite differently than $L_{\mathcal{C}}(\operatorname{Mod}(S))$ and $L_{\mathcal{C}}(\mathscr{N}_k(S))$. The main purpose of this paper is to prove the following result.

Theorem 1.1. For any type (p,1) with p>1, $L_{\mathcal{C}}(\mathscr{F})=1$.

We may find a filling closed geodesic \tilde{c} on \tilde{S} and a vertex $\tilde{u} \in \mathcal{C}_0(\tilde{S})$ so that \tilde{u} intersects \tilde{c} only once. Let $u \in \mathcal{C}_0(S)$ be the vertex obtained from \tilde{u} by removing x. Let $f \in \mathscr{F}$ be a pseudo-Anosov element obtained from pushing x along \tilde{c} (see Theorem 2 of [7]). From [15], we know that $\{u, f(u)\}$ forms the boundary of an x-punctured cylinder on S. This means that i(u, f(u)) = 0, where and below $i(\alpha, \beta)$ denotes the geometric intersection number between two vertices $\alpha, \beta \in \mathcal{C}_0(S)$. Note, since f is a homeomorphism of S, that $i(f(u), f^2(u)) = 0$. Hence f(u) is disjoint from both u and $f^2(u)$. By the definition of $d_{\mathcal{C}}$, we have $d_{\mathcal{C}}(u, f^2(u)) \leq 2$. Hence from the construction of f, u intersects $f^2(u)$, which implies that $d_{\mathcal{C}}(u, f^2(u)) > 1$. We conclude that $d_{\mathcal{C}}(u, f^2(u)) = 2$. Now we modify the argument of [4]. Since f is a homeomorphism of S, we obtain

$$d_{\mathcal{C}}(f^{2m}(u), f^{2m-2}(u)) = 2 \text{ for } m = 1, 2, \dots.$$

Now the triangle inequality yields $d_{\mathcal{C}}(f^{2m}(u), u) \leq 2m$, which says

$$\frac{d_{\mathcal{C}}\left(f^{2m}(u), u\right)}{2m} \le 1$$

for all positive integers m. It follows from (1.1) that $\tau_{\mathcal{C}}(f) \leq 1$ and thus that $L_{\mathcal{C}}(\mathscr{F}) \leq 1$. The assertion that $L_{\mathcal{C}}(\mathscr{F}) \geq 1$ follows from the following result.

Theorem 1.2. Let S be of type (p,1) with p > 1 and let $f \in \mathscr{F}$ be a pseudo-Anosov element. Then there is $u \in \mathcal{C}_0(S)$ such that for any integer m with $|m| \geq 3$, we have

$$(1.2) d_{\mathcal{C}}(u, f^m(u)) \ge |m|.$$

Remark. Theorem 1.2 is compared with Proposition 3.6 of [8], which states that there is a constant c = c(p, n), c > 0, such that $d_{\mathcal{C}}(u, f^m(u)) \ge c|m|$ for all pseudo-Anosov maps f and all $u \in \mathcal{C}_0(S)$. The quantitative estimation for c is, however, largely unknown.

Outline of Proof. Let **H** be a hyperbolic plane and $\varrho : \mathbf{H} \to \tilde{S}$ the universal covering map with a covering group G. Then G is purely hyperbolic. There is an essential hyperbolic element $g \in G$ that corresponds to f (Theorem 2 of [7]).

In the case where S contains only one puncture x, all vertices u in $C_0(S)$ are non-preperipheral, in the sense that u is homotopic to a non-trivial simple closed geodesic on \tilde{S} as x is filled in. Thus, for each vertex $u_0 \in C_0(S)$, there defines a configuration $(\tau_0, \Omega_0, \mathcal{U}_0)$ that corresponds to u_0 . See Section 2 for expositions.

Note that $\tau_{\mathcal{C}}(f)$ does not depend on choices of $u \in \mathcal{C}_0(S)$. A non-preperipheral vertex $u_0 \in \mathcal{C}_0(S)$ can be selected so that $\Omega_0 \cap \operatorname{axis}(g) \neq \emptyset$ and $i(\varrho(\operatorname{axis}(g)), \tilde{u}) \geq 2$, where we use the similar notation $i(\tilde{c}, \tilde{u})$ to denote the intersection number between a vertex \tilde{u} and a filling curve \tilde{c} (we always assume that \tilde{u} intersects \tilde{c} at non self-intersection points of \tilde{c} by performing a small perturbation if necessary). For $m \geq 3$, let u_m be the geodesic homotopic to the image curve $f^m(u_0)$. Suppose that

$$[u_0, u_1, \cdots, u_s, u_m]$$

is an arbitrary geodesic path in the 1-skeleton of $\mathcal{C}(S)$ that connects u_0 and u_m with a minimum number of sides. Then all u_j , $1 \leq j \leq s$, are non-preperipheral, which allows us to obtain the configurations $(\tau_j, \Omega_j, \mathcal{U}_j)$ determined by the vertices u_j . Note that the sequence $\mathbf{H} \setminus \Delta'_j$ (See Fig. 1 and (3.1) for the construction of Δ'_j) monotonically moves down towards the attracting fixed point A of g, and the optimal scenario is so does the sequence Ω_j . In case this occurs, we will show that the average rate of the movement of Ω_j towards A is no faster than that of $\mathbf{H} \setminus \Delta'_j$. This leads to that $\Omega_j \cap \Delta'_m \neq \emptyset$ for $j \leq m-2$, which will imply that u_j intersects u_m as long as $j \leq m-2$. It follows that $s \geq m-1$ and thus that $d_{\mathcal{C}}(u_0, u_m) \geq m$. If m is negative and $m \leq -3$, the proof is similar.

2. Curve complex and tessellations in hyperbolic plane

Let S be of type (p, n). Due to Harvey [6], one can define the curve complex $\mathcal{C}(S)$ of dimension 3p-4+n as the following simplicial complex: vertices of $\mathcal{C}(S)$ are simple closed geodesics, and k-dimensional simplicies of $\mathcal{C}(S)$ are collections of (k+1)-tuples $\{u_0, u_1, \ldots, u_k\}$ of disjoint simple closed geodesics on S. Let $\mathcal{C}_k(S)$ denote the k-skeleton of $\mathcal{C}(S)$. We then introduce a metric $d_{\mathcal{C}}$, called the path metric, in the following way. First we make each simplex Euclidean with side length one, then for any vertices $u, v \in \mathcal{C}_0(S)$, we declare the distance $d_{\mathcal{C}}(u, v)$ between u and v to be the smallest number of edges connecting u and v. The curve complex $\mathcal{C}(\tilde{S})$ is similarly defined.

Throughout the rest of the paper we assume that S is a closed Riemann surface minus one point x. By forgetting the puncture x, we can define a fibration tructure $\mathcal{C}(S) \to \mathcal{C}(\tilde{S})$ that admits a global section (since any vertex in $\mathcal{C}_0(\tilde{S})$ can be naturally thought of as a vertex in $\mathcal{C}_0(S)$). For each $\tilde{\varepsilon} \in \mathcal{C}_0(\tilde{S})$, let $F_{\tilde{\varepsilon}}$ be the fiber over $\tilde{\varepsilon}$ that consists of $u \in \mathcal{C}_0(S)$ for which $\tilde{u} = \tilde{\varepsilon}$, where \tilde{u} is homotopic to u if u is viewed as curves on \tilde{S} .

Fix $\tilde{\varepsilon} \in C_0(\tilde{S})$. Let $\varrho^{-1}(\tilde{\varepsilon})$ denote the collection of geodesics $\hat{\varepsilon}$ in \mathbf{H} such that $\varrho(\hat{\varepsilon}) = \tilde{\varepsilon}$. Since $\tilde{\varepsilon}$ is simple, all geodesics in $\varrho^{-1}(\tilde{\varepsilon})$ are mutually disjoint. It is also clear that $\varrho^{-1}(\tilde{\varepsilon})$ gives rise to a partition of \mathbf{H} . Let $\mathscr{R}_{\tilde{\varepsilon}}$ be the set of components of $\mathbf{H} \setminus \varrho^{-1}(\tilde{\varepsilon})$. By Lemma 2.1 of [16], there is a bijection $\chi : \mathscr{R}_{\tilde{\varepsilon}} \to F_{\tilde{\varepsilon}}$. Each $\Omega \in \mathscr{R}_{\tilde{\varepsilon}}$ tessellates the hyperbolic plane \mathbf{H} under the action of G. See [16] for more information on the tessellation.

Let $\Omega \in \mathscr{R}_{\tilde{\varepsilon}}$. The Dehn twist $t_{\tilde{\varepsilon}}$ can be lifted to a map $\tau : \mathbf{H} \to \mathbf{H}$ so that the restriction $\tau|_{\Omega} = \mathrm{id}$. Observe that the complement of the closure of Ω is a disjoint union of half-planes. Each such half plane Δ includes infinitely many geodesics in $\varrho^{-1}(\tilde{\varepsilon})$, and no geodesics in $\varrho^{-1}(\tilde{\varepsilon})$ are contained in Ω . Thus, there defines infinitely many half planes contained in Δ . Let \mathscr{U} be the collection of all such half planes. Obviously \mathscr{U} is a partially ordered set defined by inclusion. Maximal elements of \mathscr{U} are called first order elements (Δ is one of them), elements of \mathscr{U} that are included in a maximal element but are not included in any other elements of \mathscr{U} are called second order elements, and so on. We see that for any element Δ_n of order n with $n \geq 2$, there is a unique element Δ_{n-1} of order n-1 such that $\Delta_n \subset \Delta_{n-1}$. Conversely, for each $\Delta_{n-1} \in \mathscr{U}$ of order n-1, there are infinitely many disjoint elements $\Delta_n \in \mathscr{U}$ of order n that are contained in Δ_{n-1} .

Each maximal element Δ is an invariant half plane under the action of τ ; and element $\Delta' \subset \Delta$ of any other order is not τ -invariant, but τ sends Δ' to an element $\Delta'' \subset \Delta$ of the same order. The map τ is quasiconformal and extends to a quasisymmetric map on \mathbf{S}^1 . See [14] for more details.

Let $\Omega \in \mathscr{R}_{\tilde{\varepsilon}}$ be such that $\chi(\Omega) = u$ for some $u \in \mathcal{C}_0(S)$. We call the triple $(\tau, \Omega, \mathscr{U})$ the configuration corresponding to u. Write $\tau_u = \tau$, $\Omega_u = \Omega$ and $\mathscr{U}_n = \mathscr{U}$ to emphasize this correspondence.

For i=1,2, let $u_i \in \mathcal{C}_0(S)$, and let $(\tau_i,\Omega_i,\mathcal{U}_i)$ be the configurations corresponding to u_i . If $\tilde{u}_1=\tilde{u}_2=\tilde{\varepsilon}$, i.e., $u_i\in F_{\tilde{\varepsilon}}$, then $\Omega_i\in \mathcal{R}_{\tilde{\varepsilon}}$. Since $\mathcal{R}_{\tilde{\varepsilon}}$ is G-invariant, there is $h\in G$ such that $h(\Omega_1)=\Omega_2$. Obviously, $\Omega_1=\Omega_2$ if and only if $h=\operatorname{id}$. Suppose now that $\Omega_1\neq\Omega_2$. Then Ω_1 is disjoint from Ω_2 , and there is a path Γ in $F_{\tilde{\varepsilon}}$ connecting $u_1=\chi(\Omega_1)$ and $u_2=\chi(\Omega_2)$ (Proposition 2.4 of [16]). Unfortunately, there is no guarantee that Γ is a geodesic path in $\mathcal{C}_1(S)$. When Ω_1 and Ω_2 are adjacent, i.e., $\bar{\Omega}_1\cap\bar{\Omega}_2$ is a geodesic in $\varrho^{-1}(\tilde{\varepsilon})$, then it can be shown that $\{\chi(\Omega_1),\chi(\Omega_2)\}$ forms the boundary of an x-punctured cylinder on S. In particular, we assert that $d_{\mathcal{C}}(\chi(\Omega_1),\chi(\Omega_2))=1$. See [16] for more details.

In the case where $\tilde{u}_1 \neq \tilde{u}_2$, the relationship between $\mathcal{R}_{\tilde{u}_1}$ and $\mathcal{R}_{\tilde{u}_2}$ is more complicated. However, if there are $u_1 \in F_{\tilde{u}_1}$ and $u_2 \in F_{\tilde{u}_2}$ such that u_1 is disjoint from u_2 , then \tilde{u}_1 is disjoint from u_2 , which implies that $\varrho^{-1}(\tilde{u}_1)$ is disjoint from $\varrho^{-1}(\tilde{u}_2)$. We have the following result which was proved in [15].

Lemma 2.1. Suppose that u_1, u_2 are disjoint with $\tilde{u}_1 \neq \tilde{u}_2$. Then $\Omega_1 \cap \Omega_2 \neq \emptyset$. Moreover, each maximal element of \mathcal{U}_1 contains or is contained in a maximal element of \mathcal{U}_2 , and vise versa.

Remark. If a maximal element $\Delta_1 \in \mathcal{U}_1$ contains a maximal element of \mathcal{U}_2 , then Δ_1 contains infinitely many maximal elements of \mathcal{U}_2 ; but if $\Delta_1 \in \mathcal{U}_1$ is contained in a maximal element Δ_2 of \mathcal{U}_2 , then such a Δ_2 is unique. The same is true for maximal elements of \mathcal{U}_2 .

By assumption, S contains only one puncture, which means that any mapping class must fix the puncture. It turns out that the x-pointed mapping class group (which is defined as a group that consists of mapping classes fixing x) is the same as the ordinary mapping class group Mod(S). It is well-known (Theorem 4.1 and Theorem 4.2 of Birman [2]) that there exists an exact sequence

$$(2.1) 0 \longrightarrow \pi_1(\tilde{S}, x) \longrightarrow \operatorname{Mod}(S) \longrightarrow \operatorname{Mod}(\tilde{S}) \longrightarrow 0,$$

which defines an injective map $\psi: G \to \operatorname{Mod}(S)$ (since G is canonically isomorphic to $\pi_1(\tilde{S}, x)$). Let Q(G) be the group of quasiconformal automorphisms of \mathbf{H} . We introduce an equivalence relation " \sim " in Q(G) as follows. Two element $w_1, w_2 \in Q(G)$ are declared to be equivalent (write as $w_1 \sim w_2$) if $w_1 = w_2$ on $\partial \mathbf{H} = \mathbf{S}^1$. The quotient group $Q(G)/\sim$ is isomorphic to $\operatorname{Mod}(S)$ via a "Bers isomorphism" φ [1]. Notice that G is naturally regarded as a normal subgroup of $Q(G)/\sim$, φ restricts to the injective map ψ defined by (2.1), and we have $\varphi(G) = \psi(G) = \mathscr{F}$. For each element $h \in G$, let $h^* \in \mathscr{F} \subset \operatorname{Mod}(S)$ denote the mapping class $\varphi(h) = \psi(h)$.

3. Partitions and regions in hyperbolic plane determined by vertices

Let $f \in \mathscr{F}$ be a pseudo-Anosov element. By Theorem 2 of [7], there is $g \in G$ such that $g^* = f$ and g is an essential hyperbolic element, which means that the projection $\tilde{c} := \varrho(\operatorname{axis}(g))$ is an oriented filling closed geodesic on \tilde{S} , where $\operatorname{axis}(g)$ denotes the axis of g which is an invariant geodesic in \mathbf{H} under the action of g.

Choose $\tilde{u}_0 \in \mathcal{C}_0(\tilde{S})$ so that $i(\tilde{u}_0, \tilde{c}) \geq 2$ (there are infinitely many such \tilde{u}_0). Let $\Omega_0 \in \mathscr{R}_{\tilde{u}_0}$ be such that $\Omega_0 \cap \operatorname{axis}(g) \neq \emptyset$. Then Ω_0 determines a configuration $(\tau_0, \Omega_0, \mathscr{U}_0)$ that corresponds to a vertex $\chi(\Omega_0) = u_0 \in F_{\tilde{u}_0} \subset \mathcal{C}_0(S)$.

By Lemma 3.1 of [15], $\operatorname{axis}(g)$ can not be completely included in Ω_0 , which means that there are maximal elements $\Delta_0, \Delta_0^* \in \mathcal{U}_0$ such that $\operatorname{axis}(g)$ crosses both Δ_0 and Δ_0^* . We may assume that Δ_0 and Δ_0^* cover attracting and repelling fixed points of g, respectively. Δ_0 and Δ_0^* are shown in Fig. 1.

For $m \geq 3$, let u_m denote the geodesic homotopic to the image of u_0 under the map f^m . Then u_m is also a non-preperipheral geodesic and

$$(\tau_m, \Omega_m, \mathscr{U}_m) := (g^m \tau_0 g^{-m}, g^m(\Omega_0), g^m(\mathscr{U}_0))$$

is the configuration corresponding to u_m . In particular, $\Delta'_m := g^m(\Delta_0^*)$ is a maximal element of \mathcal{U}_m that covers the repelling fixed point B of g. Δ'_m is also drawn in Fig. 1.

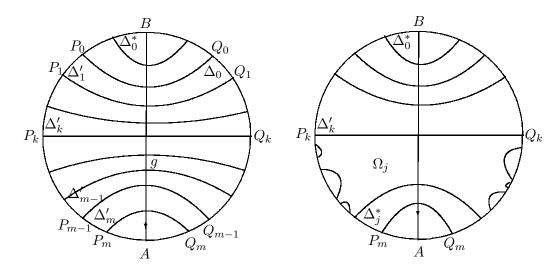


Fig. 1 Fig. 2

In what follows, we use the symbol $\overline{P_iQ_i}$ to denote the geodesic in \mathbf{H} connecting points P_i and Q_i on \mathbf{S}^1 . Also, for any two non-antipodal points $X,Y \in \mathbf{S}^1$, let (XY) denote the unoriented smaller arc on \mathbf{S}^1 connecting X and Y. Likewise, we use $(XZ1 \cdots Z_nY)$ to denote the arc on \mathbf{S}^1 that connects X and Y and passes through points Z_1, \dots, Z_n in order on \mathbf{S}^1 .

We thus have $\overline{P_0Q_0} = \partial \Delta_0$. Denote by

(3.1)
$$\Delta'_{j} = g^{j}(\Delta_{0}^{*}) \text{ for } j = 1, 2, \dots, m,$$

and let $\overline{P_jQ_j} = \partial \Delta'_j$. By inspecting Fig. 1, we find that for $1 \leq j \leq m-1$,

$$(3.2) g(\overline{P_j Q_j}) = \overline{P_{j+1} Q_{j+1}}$$

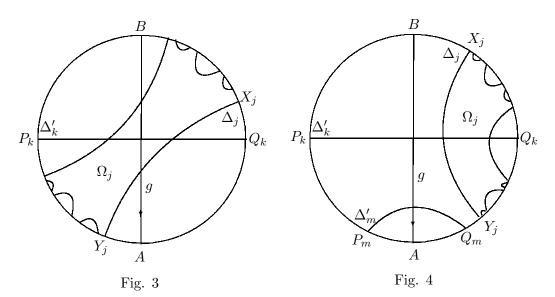
and that $\overline{P_{j}Q_{j}}$ is disjoint from $\overline{P_{j+1}Q_{j+1}}$. Furthermore, for $1 \leq j \leq m-2$,

(3.3)
$$g(P_i P_{i+1}) = (P_{i+1} P_{i+2})$$
 and $g(Q_i Q_{i+1}) = (Q_{i+1} Q_{i+2})$.

It is also clear that $\overline{P_jQ_j}$ lies above $\overline{P_kQ_k}$ whenever $k>j\geq 1$. Since $i(\tilde{c},\tilde{u})\geq 2$, we assert that $\overline{P_0Q_0}$ lies above $\overline{P_1Q_1}$ ($\overline{P_0Q_0}=\overline{P_1Q_1}$ if and only if $i(\tilde{u},\tilde{c})=1$). See Fig. 1. All these geodesics $\overline{P_jQ_j}$ give rise to a partition of the hyperbolic plane \mathbf{H} . Note that Ω_0 is the complement of all maximal elements of \mathscr{U}_1 . We have $\Omega_0\subset \mathbf{H}\setminus(\Delta_0\cup\Delta_0^*)$ and $\Omega_m\subset\mathbf{H}\setminus\Delta_m'$.

Suppose that a geodesic path (1.3) in $C_1(S)$ connects u_0 and u_m , which tells us that $d_{\mathcal{C}}(u_j, u_{j+1}) = 1$ for $j = 0, \dots, s-1$, and $d_{\mathcal{C}}(u_s, u_m) = 1$. We need to show that $s \geq m-1$.

Since all u_j are non-preperipheral, we can obtain the configurations $(\tau_j, \Omega_j, \mathscr{U}_j)$ corresponding to those u_j . Fix k with $1 \leq k \leq s$. A region Ω_j , $1 \leq j \leq s$, is called to be located at level k if $\Delta_j = \Delta'_k$ for some maximal element $\Delta_j \in \mathscr{U}_j$. Similarly, Ω_j is called to be located above level k if $\Omega_j \cap \Delta'_k \neq \emptyset$. Fig. 2 demonstrates the situation where Ω_j is located at level k, while Fig. 3, 4, 5 and 6 are all possible cases where Ω_j are located above level k.

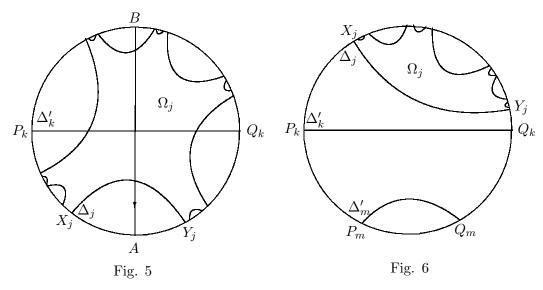


By Lemma 3.1 of [15], $\operatorname{axis}(g)$ is not included in any Ω_j . That is, either $\operatorname{axis}(g)$ is contained in a maximal element of \mathcal{U}_j , or $\operatorname{axis}(g)$ intersects $\partial \Delta_j$ and $\partial \Delta_j^*$ for maximal elements Δ_j and Δ_j^* of \mathcal{U}_j . In both case, we may find a maximal $\Delta_j \in \mathcal{U}_j$, shown in Fig. 3, 4, 5, or 6, that covers the attracting fixed point A of g.

Lemma 3.1. Suppose that Ω_j is located above level k with $k \leq m-1$ (Fig. 3,4,5,6). Let $\Delta_j \in \mathscr{U}_j$ be the maximal element that covers the attracting fixed point of g. Then at least one point of $\{X_j, Y_j\} := \partial \Delta_j \cap \mathbf{S}^1$, X_j say, lies above $\overline{P_{k+1}Q_{k+1}}$.

Proof. By assumption, $\Omega_j \cap \Delta'_k \neq \emptyset$. If $\Omega_j \subset \Delta'_k$ (Fig. 6), then for the Δ_j shown in Fig. 6, $\{X_j, Y_j\}$ both lie above $\overline{P_k Q_k}$. So both $\{X_j, Y_j\}$ lie above $\overline{P_{k+1} Q_{k+1}}$. Suppose now that Ω_j is not a subset of Δ'_k and $\overline{P_k Q_k}$ crosses Δ_j (Fig. 3, 4), then we see that X_j lies above $\overline{P_{k+1} Q_{k+1}}$.

It remains to consider the case where $\overline{P_kQ_k}$ is disjoint from Δ_j (Fig. 5). Then Δ_j lies below $\overline{P_kQ_k}$ and intersects axis(g). If both $\{X_j,Y_j\}$ lie below $\overline{P_{k+1}Q_{k+1}}$, then by Lemma 2.1 of [12], (3.2) and (3.3) we can find a maximal element $\Delta_j^* \in \mathscr{U}_j$ that covers Δ_k' . Note that $\Omega_j \subset \mathbf{H} \setminus (\Delta_j \cup \Delta_j^*)$. We conclude that Ω_j is disjoint from Δ_k' . This is a contradiction.



Lemma 3.2. Suppose that Ω_j is located above level k for $1 \leq k \leq m-1$. Let $\Delta_j \in \mathcal{U}_j$ be the maximal element obtained from Lemma 3.1. Then we have (i) Δ_j is not contained in Δ'_m , (ii) Δ_j is not disjoint from axis(g), and (iii) $\Delta_j \cap \Delta'_m \neq \emptyset$.

Proof. Properties (i) and (ii) follow directly from the construction of Δ_j (by noting that Δ_j covers the attracting fixed point of g while Δ'_m does not). For (iii), we write $\{X_j,Y_j\}=\partial\Delta_j$. By Lemma 3.1, at least one point of $\{X_j,Y_j\}$, X_j say, lies above $\overline{P_mQ_m}$. If both X_j and Y_j lie above $\overline{P_mQ_m}$ (Fig. 6 with k=m), then Δ_j satisfies the conditions (i)-(iii) of the lemma. We are done. If only X_j lies above $\overline{P_mQ_m}$, then either $\Delta_j \supset \operatorname{axis}(g)$ (Fig. 4 with k=m), in which case, Δ_j satisfies the conditions (i)-(iii) of the lemma), or X_j and Y_j are separated by $\operatorname{axis}(g)$ (Fig. 3 with k=m), in which case, $\partial\Delta_j\cap\operatorname{axis}(g)\neq\emptyset$. It is easy to see that Δ_j is not contained in Δ'_m and $\Delta_j\cap\Delta'_m\neq\emptyset$.

If both X_j, Y_j lie below $\overline{P_kQ_k}$ (Fig. 5), by Lemma 3.1, at least one point of $\{X_j, Y_j\}$ lies above $\overline{P_{k+1}Q_{k+1}}$. Since $k+1 \leq m$, we conclude that $\Delta_j \cap \Delta'_m \neq \emptyset$ and thus conditions (i)-(iii) remains valid.

Lemma 3.3. If Ω_i is located above level m-1, or at level m-2, then $d_{\mathcal{C}}(u_i, u_m) \geq 2$.

Proof. First assume that Ω_j is located above level m-1. By Lemma 3.2, there is a maximal $\Delta_j \in \mathscr{U}_j$ such that Δ_j is not contained in Δ'_m and $\Delta_j \cap \Delta'_m \neq \emptyset$. If $\partial \Delta_j \cap \partial \Delta'_m \neq \emptyset$, then \tilde{u}_j intersects \tilde{u}_m , where \tilde{u}_j is the geodesic on \tilde{S} homotopic to u_j if u_j is viewed as a curve on \tilde{S} . Hence u_j intersects u_m and the assertion follows.

Assume now that $\partial \Delta_j \cap \partial \Delta'_m = \emptyset$. Then $\Delta_j \cap \mathbf{S}^1 \supset (P_m A Q_m)$. In this case, $\Omega_j \subset \mathbf{H} \setminus (\Delta_j \cup \Delta_j^*)$ is disjoint from $\mathbf{H} \setminus \Delta'_m$. But $\Omega_m \subset \mathbf{H} \setminus \Delta'_m$. Hence Ω_j is disjoint from Ω_m . It follows from Lemma 2.1 that $d_{\mathcal{C}}(u_j, u_m) \geq 2$.

Now suppose that Ω_j is located at level m-2 (Fig. 2 with k=m-2). Then there is maximal $\Delta_j \in \mathscr{U}_j$ such that $\Delta_j = \Delta'_{m-2}$. Again, by Lemma 2.1 of [12], there is a maximal $\Delta_j^* \in \mathscr{U}_j$, shown in Fig. 2, so that Δ_j^* is disjoint from Δ_j , such that $\partial \Delta_j^*$ intersects axis(g) and Δ_j^* contains $\mathbf{H} \setminus \Delta'_{m-1}$. In particular, we see that $\Delta_j^* \cap \Delta'_m \neq \emptyset$. The assertion follows from Lemma 2.1.

Remark. The bound m-2 is optimal. In fact, if Ω_j is located at level m-1, then $\Omega_j \subset \Delta'_m \backslash \Delta'_{m-1}$ and it could be the case that $d_{\mathcal{C}}(\chi(\Omega_j), u_m) = d_{\mathcal{C}}(u_j, u_m) = 1$. See Lemma 2.3 of [16].

4. Proof of Theorem 1.2

We only treat the case where m > 0. Theorem 1.2 was proved when m = 3, 4 (by Theorem 1.1 of [12] and Theorem 1.1 of [15]). So we assume that $m \ge 5$. Note that all u_j , $j = 1, 2, \dots, s$, are non-preperipheral geodesics, which allow us to acquire the configurations $(\tau_j, \Omega_j, \mathscr{U}_j)$ for $j = 1, 2, \dots, s$.

We first verify that Ω_1 is located above or at level 1. Suppose not. Then $\Omega_1 \cap \Delta_1' = \emptyset$ and there is no maximal element of \mathscr{U}_1 that equals Δ_1' . There is a maximal element $\Delta_1 \in \mathscr{U}_1$ such that $\Delta_1' \subset \Delta_1$. In particular, $\Delta_1 \cap \Delta_0 \neq \emptyset$, $\partial \Delta_1 \cap \partial \Delta_0 = \emptyset$ and $\Delta_1 \cup \Delta_0 = \mathbf{H}$. This implies that $\mathbf{H} \setminus \Delta_1$ is disjoint from $\mathbf{H} \setminus \Delta_0$. So Ω_1 is disjoint from Ω_0 . Hence by Lemma 2.1, $d_{\mathcal{C}}(u_0, u_1) \geq 2$. This is a contradiction.

By induction hypothesis, suppose that Ω_j , $j \leq m-3$, is located above or at level j. We need to show that Ω_{j+1} is located above or at level j+1. Otherwise, suppose that Ω_{j+1} is located neither above nor at level j+1. There is a maximal element $\Delta''_{j+1} \in \mathscr{U}_{j+1}$ that contains $\Delta'_{j+1} (= g^{j+1}(\Delta_0^*))$, which says that $\partial \Delta''_{j+1}$ lies below $\overline{P_{j+1}Q_{j+1}}$. By assumption, Ω_j is located above or at level j.

Case 1. Ω_j is located above level j (Fig. 3, 4, 5, 6). By Lemma 3.2, there is a maximal element $\Delta_j \in \underline{\mathscr{U}_j}$, which covers the attracting fixed point A of g, such that either $\partial \Delta_j$ lies above $\overline{P_{j+1}Q_{j+1}}$ or $\partial \Delta_j$ intersects $\overline{P_{j+1}Q_{j+1}}$. Both cases would imply that $\Delta_j \cap \Delta''_{j+1} \neq \emptyset$ and thus that u_j and u_{j+1} intersect. This contradicts that $d_{\mathcal{C}}(u_j, u_{j+1}) = 1$.

Case 2. Ω_j is located at level j (Fig. 2), then there is a maximal $\Delta_j \in \mathscr{U}_j$ such that $\Delta_j = \Delta'_j (= g^j(\Delta_0^*))$. Let $\Delta_j^* \in \mathscr{U}_j$ be the maximal element that contains $g(\mathbf{H} \setminus \Delta_j)$.

Then either $\partial \Delta_j^*$ lies above $\overline{P_{j+1}Q_{j+1}}$, or $\partial \Delta_j^* = \overline{P_{j+1}Q_{j+1}}$. Note that $\partial \Delta_{j+1}''$ lies below $\overline{P_{j+1}Q_{j+1}}$. We conclude that in both cases $\Delta_j^* \cap \Delta_{j+1}'' \neq \emptyset$. This again implies that u_j and u_{j+1} intersect, contradicting that $d_{\mathcal{C}}(u_j, u_{j+1}) = 1$.

We conclude that for all j with $j \leq m-2$, Ω_j is located above or at level j. In particular, Ω_{m-2} is located above or at level m-2. If Ω_{m-2} is located above level m-2, then it lies above level m-1. By Lemma 3.3, $d_{\mathcal{C}}(u_{m-2}, u_m) \geq 2$. If Ω_{m-2} is located at level m-2, then again Lemma 3.3 says that $d_{\mathcal{C}}(u_{m-2}, u_m) \geq 2$. This proves that $s \geq m-1$ and thus that $d_{\mathcal{C}}(u_0, u_m) \geq m$.

Remark. From the proof we also deduce that $d_{\mathcal{C}}(u_0, u_m) = m$ if and only if $\Omega_0 \cap \operatorname{axis}(g) \neq \emptyset$ and $i(\tilde{c}, \tilde{u}_0) = 1$. In this case, all u_j are non preperipheral geodesic and for every $j = 1, \dots, m-1$, Ω_j is located at level j. Since $i(\tilde{c}, \tilde{u}_0) = 1$, we see that $P_0 = P_1$ and $Q_0 = Q_1$. Also in the terminology of [16], for $j = 0, \dots, m-1$, Ω_j is adjacent to Ω_{j+1} , and thus $D(\Omega_j, \Omega_{j+1}) = 1$. It follows that $d_{\mathcal{C}}(u_0, u_m) = \sum_{j=0}^{m-1} D(\Omega_j, \Omega_{j+1}) = m$.

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